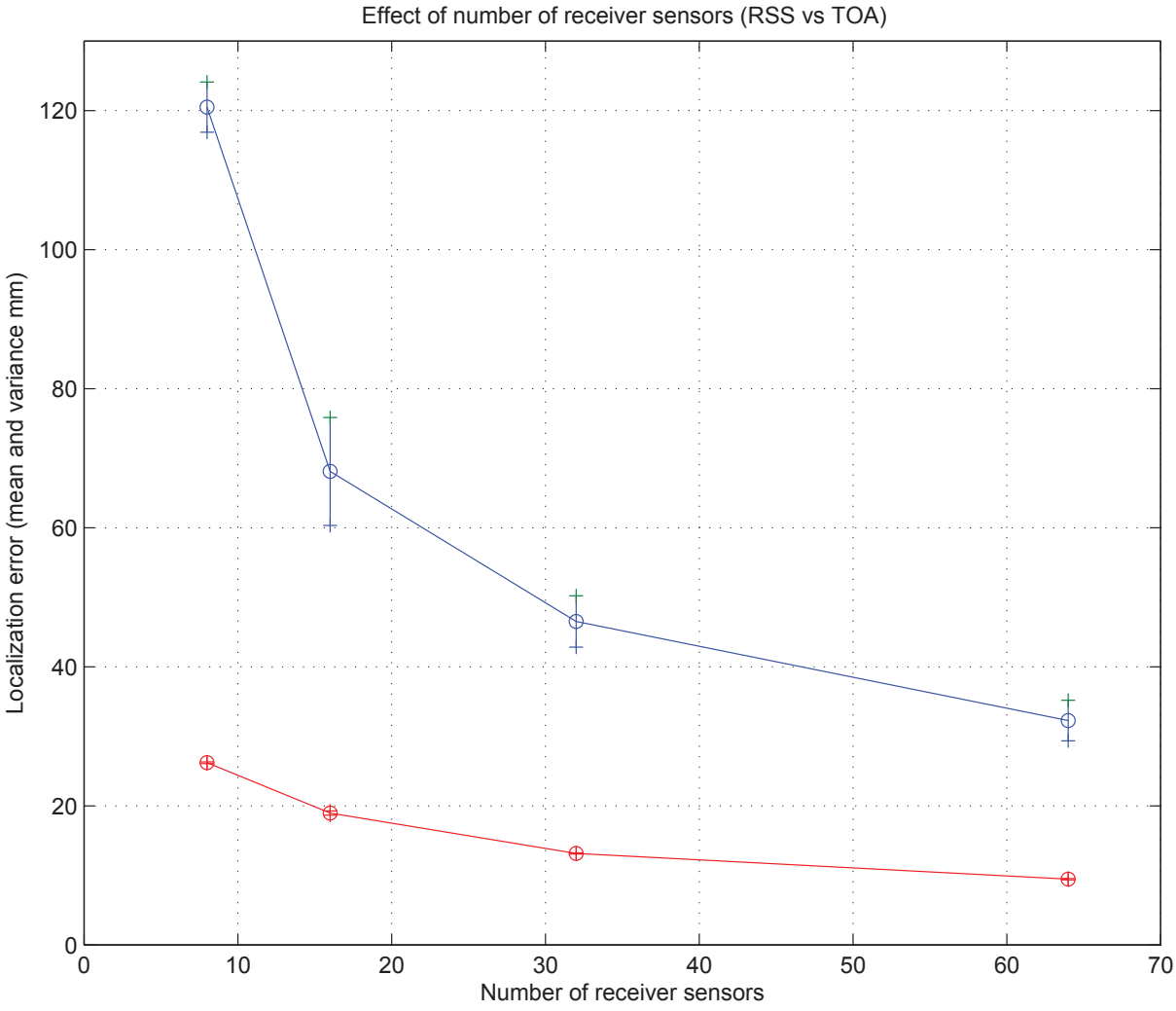
Effect of number of receiver sensors (RSS vs TOA)
Localization error (mean and variance mm)
Number of receiver sensors
0
20
40
60
80
100
120
0
10
20
30
40
50
60
70